## S450H

## 24V Hydraulic Swing Gate Operator



Intertek
UL325 - UL991

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## IMPORTANT SAFETY INFORMATION

Important Safety Instructions

## WARNING - TO REDUCE THE RISK OF SEVERE INJURY OR DEATH:

- READ AND FOLLOW ALL INSTRUCTIONS.
- Never let children operate or play with the gate controls. Keep remote controls away from children.
- Always keep people and objects away from the gate. NO ONE SHOULD CROSS THE PATH OF A MOVING GATE.
- Test the gate operator monthly. The gate MUST reverse on contact with a rigid object or when an object activates a non-contact sensor. If necessary, adjust the force or the limit of travel and then retest the gate operator. Failure to properly adjust and retest the gate operator can increase the risk of injury or death.
- Use the manual release mechanism only when the gate is not moving.
- KEEP GATE PROPERLY MAINTAINED. Have a qualified service person make repairs to gate hardware.
- The entrance is for vehicles only. Pedestrians must use a separate entrance.
- SAVE THESE INSTRUCTIONS.


## Important Installation Instructions

1. Install the gate operator only when the following conditions have been met:

- The operator is appropriate for the type and usage class of the gate.
- All openings of a horizontal slide gate have been guarded or screened from the bottom of the gate to a minimum of 4 feet ( 1.25 m ) above the ground to prevent a 2.25 inch ( 55 mm ) diameter sphere from passing through openings anywhere in the gate or through that portion of the adjacent fence that the gate covers when in the open position.
- All exposed pinch points are eliminated or guarded.
- Guarding is supplied for exposed rollers.

2. The operator is intended for installation on gates used by vehicles only. Pedestrians must be provided with a separate access opening.
3. To reduce the risk of entrapment when opening and closing, the gate must be installed in a location that allows adequate clearance between the gate and adjacent structures. Swinging gates shall not open outward into public access areas.
4. Before installing the gate operator, ensure that the gate has been properly installed and that it swings freely in both directions. Do not over-tighten the operator clutch or pressure relief valve to compensate for a damaged gate.
5. User controls must be installed at least 6 feet ( 1.83 m ) away from any moving part of the gate and located where the user is prevented from reaching over, under, around or through the gate to operate the controls. Controls located outdoors or those that are easily accessible shall have security features to prevent unauthorized use.
6. The Stop and/or Reset buttons must be located within line-of-sight of the gate. Activation of the reset control shall not cause the operator to start.
7. All warning signs and placards must be installed and easily seen within visible proximity of the gate. A minimum of one warning sign shall be installed on each side of the gate.
8. For gate operators that utilize a non-contact sensor (photo beam or the like):

- See instructions on the placement of non-contact sensors for each type of application.
- Exercise care to reduce the risk of nuisance tripping, such as when a vehicle trips the sensor while the gate is still moving.
- Locate one or more non-contact sensors where the risk of entrapment or obstruction exists, such as at the reachable perimeter of a moving gate or barrier.
- Use only "FAAC Photobeam" or "EMX IRB-RET" photoelectric eyes to comply with UL325.


## Important Installation Instructions (continued)

9. For gate operators that utilize a contact sensor (edge sensor or similar):

- Locate one or more contact sensors where the risk of entrapment or obstruction exists, such as at the leading edge, trailing edge, and post mounted both inside and outside of a vehicular horizontal slide gate
- Locate one or more contact sensors at the bottom edge of a vehicular vertical lift gate.
- Locate one or more contact sensors at the bottom edge of a vertical barrier (arm).
- Locate one or more contact sensors at the pinch point of a vehicular vertical pivot gate.
- Locate hard-wired contact sensors and wiring so that communication between sensor and gate operator is not subjected to mechanical damage.
- Locate wireless contact sensors, such as those that transmit radio frequency (RF) signals, where the transmission of signals are not obstructed or impeded by building structures, natural landscaping or similar hindrances. Wireless contact sensors shall function under their intended end-use conditions.
- Use only FAAC MSE MO, CN60 or M60 edge sensors.


## General Safety Precautions

## Gate Construction

Vehicular gates should be constructed and installed in accordance with ASTM F2200: Standard Specification for Automated Vehicular Gate Construction.
For more information, contact ASTM at: www.astm.org

## Installation

- If you have any questions or concerns regarding the safety of the gate operating system, do not install the operator and consult the manufacturer.
- The condition of the gate structure itself directly affects the reliability and safety of the gate operator.
- Only qualified personnel should install this equipment. Failure to meet this requirement could cause severe injury and/or death, for which the manufacturer cannot be held responsible.
- The installer must provide a main power switch that meets all applicable safety regulations.
- It is extremely unsafe to compensate for a damaged gate by increasing hydraulic pressure.
- Install devices such as reversing edges and photo beams to provide better protection for personal property and pedestrians. Install reversing devices that are appropriate to the gate design and application.
- Before applying electrical power, ensure that voltage requirements of the equipment correspond to the supply voltage. Refer to the label on your gate operator system.


## Usage

- Use this equipment only in the capacity for which it was designed. Any use other than that stated should be considered improper and therefore dangerous.
- The manufacturer cannot be held responsible for damage caused by improper, erroneous or unreasonable use.
- If a gate system component malfunctions, disconnect the main power before attempting to repair it.
- Do not impede the movement of the gate, you may injure yourself or damage the gate system as a result.
- This equipment may reach high thermal temperatures during normal operation, therefore use caution when touching the external housing of the gate operator.
- Use the manual release mechanism according to the procedures presented in this manual.
- Before performing any cleaning or maintenance operations, disconnect power to the equipment.
- All cleaning, maintenance or repair work must performed by qualified personnel.

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UL325 Gate Operator Classifications

## RESIDENTIAL VEHICULAR GATE OPERATOR CLASS I

A vehicular gate operator system intended for use in a single family dwelling, garage or associated parking area.

## COMMERCIAL / GENERAL ACCESS VEHICULAR GATE OPERATOR CLASS II

A vehicular gate operator system intended for use in commercial locations or buildings such as multi-family housing units (five or more single family units), hotels, parking garages, retail stores or other buildings that service the general public.

## INDUSTRIAL / LIMITED ACCESS VEHICULAR GATE OPERATOR CLASS III

A vehicular gate operator system intended for use in industrial locations or buildings such as factories, loading docks or other locations not intended to service the general public.

## restricted access vehicular gate operator class iv

A vehicular gate operator system intended for use in guarded industrial locations or buildings such as airport security areas or other restricted access locations that do not service the general public, and in which unauthorized access is prevented via supervision by security personnel.

## Installing the Warning Signs

This FAAC swing gate operator is supplied with two warning signs to alert people that a possible hazard exists and that appropriate actions should be taken to avoid the hazard or to reduce exposure to it.

Permanently install one warning sign on each side of the gate so they are fully visible to traffic and pedestrians.

Use appropriate hardware such as metal screws (not supplied) to permanently install each warning sign.

| ! MABME |
| :---: |
|  |
| Moving Gate Can Cause Serious Injury or Death KEEP CLEAR! Gate may move at any time without prior warning. <br> Do not let children operate the gate or play in the gate area. <br> Pedestrians must use separate entrance. |

## S450H OPERATOR

## 1. DESCRIPTION AND TECHNICAL SPECIFICATIONS

The self contained FAAC S450H operator is an electro-hydraulic unit consisting of a low voltage electric motor, a pump, a valve assembly and a hydraulic cylinder, all housed in an anodized aluminum body.
The model with hydraulic locking does not require the installation of electric locks and guarantees that the leaf is mechanically locked when the motor is not running. The model without hydraulic locking needs one or more electric locks to guarantee that the leaf doesn't move when the motor is not running.

The $\mathbf{S 4 5 O H}$ operator is designed and manufactured to automate vehicular swing leaf gates. Do not use for any other purpose

$\left.\begin{array}{|l|c|c|}\hline \text { TECHNICAL } \\ \text { SPECIFICATIONS }\end{array} \left\lvert\, \begin{array}{c}\text { CBAC } \\ \text { OPERATOR }\end{array} \quad \begin{array}{c}\text { SB } \\ \text { OPERATOR }\end{array}\right.\right]$

The installer is responsible for providing the main power breaker switch, and for making sure that the entire gate system meets all applicable local electrical codes.
Make sure to locate all controls that operate the gate system at least 6 ft away from any moving parts.

### 1.1 Dimensions



### 1.2 Wiring



## 2. INSTALLATION

### 2.1 Preliminary Checks

Ensure that the following conditions have been met to ensure safety and the efficient operation of the automated system:

- The gate structure must be suitable for automation. Verify that it is sufficiently strong and that its dimensions correspond to those stated in the technical specifications.
- Verify the smooth and uniform movement of leaves, without irregular friction during the entire travel.
- Verify hinges are in good working order.
- The gate swings level.


### 2.2 Installation Dimensions With Bracket Fastened To The Column

ATTENTION: do not cut the rear bracket for any reason.
Refer to Figures 4 and 5 and Table 1 to determine the installation position of the operator.


- ATTENTION: USE POSITIVE STOPS IN ORDER NOT TO EXCEED THE MAXIMUM OPENING ANGLES STATED IN TABLE 1 AND GUARANTEE THE CORRECT OPERATION OF THE AUTOMATED SYSTEM.



### 2.3 Installation Dimensions With Bracket Fastened to the Side Wall

ATTENTION: do not cut the rear bracket for any reason.
Refer to Figures $4^{1}$ and $5^{1}$ and Table 2 to determine the installation position of the operator.


- INTERSECT THE DIMENSIONS " $\mathrm{D}^{1}$ " AND " $\mathrm{B}^{1}$ " TO OBTAIN THE MAXIMUM VALUE OF OPENING ANGLES.
- ATTENTION: USE MECHANICAL LIMIT SWITCHES IN ORDER NOT TO EXCEED THE MAXIMUM OPENING ANGLES STATED IN TABLE 2 AND GUARANTEE THE CORRECT OPERATION OF THE AUTOMATED SYSTEM.



### 2.4 Installation Steps

1. Level then weld the rear bracket to the pillar, or fix it using suitable anchors. Follow the dimensions stated in Tab. 1 (never cut the rear bracket; note that it must be installed with the word "UP" facing up as shown in Figure 6 Ref. a).

2. Pre-assemble the fork (Fig. 7 ref. a) without tightening the nut. After choosing the hole on the rear bracket (see Table 1, white or grey boxes), install the fork (Fig. 7 ref. b). Secure in place by inserting the special pin supplied (Fig. 7 ref. C), then tighten the nut (Fig. 7 ref. d).

3. Install the encoder on the rear bracket by correctly engaging it on the pin, then attach it with the screw and nut supplied (Fig. 8 Ref. a, b).
4. Slightly press the protection cover on the rear bracket until it locks in position (Fig. 9).

5. Assemble the operator and the rear bracket using the supplied pin and nut (Fig. 10 Ref. a - b).


Fig. 10
6. Screw the swivel joint halfway into the piston rod (Fig. 11 Ref. a).
7. Unlock the operator according to Section 4.
8. If no external mechanical stop at close is present, you may use the stop point inside the operator (extend the rod completely up to its internal stop point).
9. If an external mechanical stop at close is present, extend the rod completely and then push it back 0.25 in .
10. Close the gate leaf and install the front bracket on the rod as shown in Fig. 11 Ref. b.


11. Establish the fixing position of the front bracket on the leaf and mark the fixing points (Fig. 12) (the operator must be perfectly level).
12. Remove the operator from the front bracket to avoid damaging the rod when the front fixing is attached on the gate.

13 Weld the front bracket directly on the leaf or attach it with threaded inserts (Fig 13)
14. If an opening mechanical stop on the ground is not installed, spacers can be used (Fig. 1 Ref. 7). Remove the front articulated joint and insert the spacers required (Fig. 14).

IMPORTANT: Overlapping bi-part gates must stop on their positive stops, one operator cannot be the stop for both gates


Fig. 13
15. Attach the operator to the front bracket (Fig. 15).
16. Remove the bleed screw (Fig. 16 Ref. a) paying special attention to leave the sealing O-Ring in place.
17. Install the metallic protection cover as shown in Fig. 16, insert and tighten both tie-rods.
18. Connect the cable to the operator using the two screws supplied, as shown in Fig. 17. Push the cord by hand, then tighten the screws


Fig. 14


## 3. MANUAL OPERATION

If the gate is to be operated manually because of a power failure or an automated system fault, activate the release device.

1. Lift the protection lid (Fig. 18, Ref. a) and insert the key in the lock (Fig. 18, Ref. b).
2. Turn the key $90^{\circ}$ clockwise to open the cover and lift it.
3. Turn the release knob (Fig. 18, Ref. c) counter-clockwise until it stops.
4. Open or close the leaf manually.

To restore the normal operation of the automated system, perform the above described operations in reverse order. Make sure to not overtighten the red knob as it is designed to strip before damaging the operator.


Fig. 18

## NOTE: The modelS450H SB with no hydraulic locks doeant' have a manual release mechanism. You do not need to release the operator to manually move the leaf.

## 4. ENCODER CONNECTIONS

The S450H operator is equipped with an encoder system. The proper assignment of the leaf to the corresponding encoder depends on the connection of the two encoder wires (leaf 1 - encoder 1 ; leaf 2 - encoder 2).
the encoder wires must be connected to the bus connector of the EO24U control board.
To verify the proper combination LEAF 1 - ENCODER 1 - MOTOR 1 and LEAF 2 - ENCODER 2 - MOTOR 2, refer to the LEDs on the encoders, as shown in Table 3 and Figures 19, 20 and 21.

To invert the leaf-encoder combination, change the encoder polarity by swapping its wires until the right LEDs are lit.


DL 1: must always be ON to ensure the right connection between encoder and board.
DL 2: identifies the leaf to which the encoder is installed.
If the encoder is installed on leaf 1 , the DL 2 LED is ON.
If the encoder is installed on leaf 2 , the DL 2 LED is OFF.
DL 3: when blinking at regular intervals, it signals the pulse reading during the leaf movement. When the gate leaf is stationary, DL 3 is OFF.

NOTE: The LEDs on the encoder also remain visible when the rear bracket protection cover is installed.

| TABLE 3 |  |  |  |
| :---: | :---: | :---: | :---: |
| LED | ON | BLINKING | OFF |
| DL 1 | Power supply ON and BUS - board <br> communication | Power supply ON but <br> no BUS communication <br> (e.g.: cabling fault) | Power supply OFF and no BUS communication <br> (e.g.: missing or broken connection) |
| DL 2 | Encoder associated to leaf 1 | 1 | Encoder associated to leaf 2 |
| DL 3 | 1 | Pulse reading during leaf movement | Leaf stationary |



Fig. 21

To change the link between encoder and leaf just swap the encoder wires, the encoder linked with leaf 1 can be coupled with leaf 2 and vice versa (see example in fig. 22)

* When leaf delay is enabled leaf 1 opens first and closes after leaf 2 . If leaf 1 and leaf 2 overlap make sure to set open and close delay on the control board.



## 5. BLEEDING

1. Loosen the tie-rods (Fig. 23 ref. a) and remove the metal protective housing (Fig. 23 ref. b).


Remove the upper tie-rod and be careful with the O-ring that must remain in its seat.
2. Remove the screw in Fig. 24 ref.d from the front bracket
3. Remove the swivel joint (Fig. 24 ref.f) from the piston. (Fig. 24 ref. g).


Fig. 24
4. Remove all spacers, if present (Fig. 25).


Fig. 25


To prevent oil leakage from the breather hole, do not tilt the operator downward

Fig. 26
5. Tilt the operator upward as much as possible. Do not force the rear fitting too much.
6. Power the operator off the batteries and repeatedly move the piston in and out, over its complete stroke, until reaching a smooth movement (Fig. 27).

7. After bleeding, repeat the operations described above in reverse order to reinstall the operator on the gate.

## 6. SPARE PARTS DIAGRAMS

## S450H CBAC



| Part | Part Number | Description |
| :---: | :--- | :--- |
| 01 | 63001885 | Skinpack |
| 02 | 2181.1 | Seal kit |
| 03 | 714019 Qt.1 | FAAC Oil: 1 qt. |
| 03 | 7140251 Qt.1 | FAAC Arctic Oil: 1 qt. |
| 04 | 63001895 | Protective Cover |
| 05 | 4170015 | Protective Cover End Cap |
| 06 | 63001905 | Tie Rod Protective Cover |
| 07 | 7119405 | Protective Cover End Cap Plug |
| 08 | 4900605 | Swivel Joint Kit (includes 9,10) |
| 09 | 702101 | Hex. Nut M10 |
| 10 | 703027 | Washer 10 mm |
| 11 | 63001945 | Front Bracket |


| Part | Part Number | Description |
| :---: | :--- | :--- |
| 12 | 63001975 | Positive Stop Spacers Kit |
| 14 | 63001985 | Manual Release Assy |
| 15 | 63001875 | Encoder |
| 16 | 63001965 | Short Pin |
| 17 | 63001915 | Rear Bracket |
| 18 | 63001935 | Molded Cable Kit |
| 19 | 63001925 | Bracket Plasitc Cover |
| 20 | 63001955 | Rear Bracket Joint |
| 21 | 7182175 | Long Pin |
| 22 | 2037 | Lock Nut 8 mm |

S450H CBAC


| Part | Part Number | Description |
| :---: | :--- | :--- |
| 01 | 63000716 | Front Flange |
| 02 | 63000656 | Piston |
| 03 | 63000646 | Cylinder |
| 04 | 63000676 | Cbac Distribution flange |
| 05 | 7090010015 | O-Ring 48 X 1.78 Mm |
| 06 | 63000756 | Plug Gasket |
| 07 | 63000766 | Plug |
| 08 | 63001985 | Manual Realease Assy |
| 09 | 63000746 | Tank Screw |
| 10 | 63000696 | 1.5 L/Min Pump |
| 11 | 701996 | Screw M4x30 Torx Ss |
| 12 | 63000626 | Motor Cover |
| 13 | 63000636 | Motor Assembly |
| 14 | 63000806 | Rear Flange |
| 15 | 63000786 | Tie Rod |


| Part | Part Number | Description |
| :---: | :--- | :--- |
| 16 | 703121 | Lock Washer M5 |
| 17 | 701985 | Screw M4x12 Torx T20 SS |
| 18 | 63000706 | Splined Joint |
| 19 | 63000776 | Motor Cover |
| 20 | 903122 | Label |
| 21 | 63001865 | Faac Sticker |
| 22 | 63000736 | Tank |
| 23 | 63000726 | Retract Tube |
| 24 | 7090815 | O-Ring Retract Tube |
| 25 | 63000013 | Gasket D80 |
| 26 | 701829 | Screw Torx M5x20 with Lock W |
| 27 | 708009 | Bushing 20X28x24.5mm |
| 28 | 63000315 | Seal |
| 29 | 7090350025 | O-Ring $34.60 \times 2.62 \mathrm{~mm}$ |
|  |  |  |

## CBAC DISTRIBUTION FLANGE



| Part | Part Number | Description |
| :---: | :--- | :--- |
| 01 | 63000816 | Valve Retainer |
| 02 | 63000816 | Valve Retainer |
| 03 | 7090050015 | 0-Ring 10.82X1.78 Mm |
| 04 | 4404085 | Lock Valve |
| 05 | 7090350025 | 0-Ring 34.60X2.62 Mm |
| 06 | 7090280015 | 0-Ring 5.28X1.78 Mm |
| 07 | 63000826 | Manual Release Valve |
| 08 | 4180315 | Shuttle Piston |
| 09 | 7090010015 | 0-Ring 4.48X1.78 Mm |
| 10 | 63000676 | CBAC Distribution flange |
| 11 | 4404095 | Inlet Valve |
| 12 | 63000836 | Valve Spacer |
| 13 | 4404065 | Inlet Valve With Spring |



| Part | Part Number | Description |
| :---: | :--- | :--- |
| 01 | 63001985 | Manual Release Assy |
| 02 | 7290445 | Release Knob |
| 03 | 7090895 | 0-Ring $21 \times 2 \mathrm{~mm}$ |
| 04 | 7131005 | Key Manual Release |
| 05 | 7275275 | Cover, Key |
| 06 | 63000666 | Release Pin |
| n/a | 7090150015 | 0-Ring Release pin |

## 1. EO24U CONTROL BOARD DESCRIPTION \& CHARACTERISTICS

This manual refers to board version 1D


### 1.1 TECHNICAL SPECIFICATIONS

| Main power supply | $115 \mathrm{~V} \sim 60 \mathrm{~Hz}$ |
| :---: | :---: |
| Secondary power supply | $\begin{gathered} 24 \text { Vdc - } 16 \text { A max. } \\ \text { (min. } 20 \text { Vdc. - max. } 36 \text { Vdc.) } \end{gathered}$ |
| Power consumption | stand-by $=4 \mathrm{~W}$ max. $=400 \mathrm{~W}$ |
| Max load per motor | 7 A |
| Accessory power | 24 Vdc - 500 mA |
| Battery charge current | 150 mA |
| Operating temperature | $-4^{\circ} \mathrm{F}+131{ }^{\circ} \mathrm{F}\left(-20^{\circ} \mathrm{C}+55^{\circ} \mathrm{C}\right)$ |
| Protection fuses | All self-resetting |
| Main power fuse | 6.3 A Timed |
| Operating Logics | E, A, S, EP, AP, SP, B, C |
| Operating time out | 10 min . |
| Pause time | Programmable (0 to 4 min) |
| Motor force, speed, obstacle sensitivity, closing delay | Programmable with dedicated trimmer |
| Connector inputs | Power supply, Battery, Radio receiver, USB |
| Terminal strip inputs | Encoder, Open A, Open B, Stop, Open safety photocell, Closing safety photocell, Limit switches |
| Terminal strip outputs | Audio Alarm, Lock, Motors, Accessory power supply |
| Programming | With trimmers, dipswitches and pushbutton |

### 1.2 LAYOUT AND COMPONENTS

| RADIO | Connector for the radio receiver |
| :--- | :---: |
| BATTERY | Connector for the backup battery |
| J24 | Jumper to disable battery charging <br> (With the jumper present the battery <br> charger is enabled) |
| POWER SUPPLY | DC Power supply input |
| TR1 to TR6 | Programming Trimmers |
| +24 LED | DC power indicator |
| SW1 - SETUP | Pushbutton for automatic setup |
| DS1 - DS2 | Programming dipswitches |
| LED ERROR | Troubleshooting indicator |
| USB A | USB connection for software upgrade |

### 1.3 RADIO CONNECTION

On the radio connector it's possible to plug in receivers RP and RP2. With a single channel radio RP it will be possible to activate only the OPEN A input, with a dual channel radio RP2 it will be possible to activate both OPEN A and OPEN B inputs. Plug in the radio board with the component side towards the internal part of the board.
A Make sure you insert or disconnect the board ONLY with the power off.

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2. INPUT / OUTPUT DESCRIPTION


| PIN | LABEL | FUNCTION |
| :---: | :---: | :---: |
| 2 EASY | 2 EASY | 2easy BUS input for encoders (S800H and S450H only), XIB and loop detector boards |
| 1 | OPEN A | N.O. Contact for total opening command |
| 2 | OPEN B / <br> CLOSE | OPEN B: N.O. Contact for opening of leaf 1 only (with only one leaf the opening stops at $50 \%$ of traveling) CLOSE (LOGIC B-C): N.O. Contact for closing command |
| 3 | STOP | N.C. Contact for stop command |
| 4 | FSW CL | N.C. Contact for closing safety |
| 5 | FSW OP | N.C. Contact for opening safety |
| 6 | GND (-) | 24 Vdc negative |
| 7 | GND (-) | 24 Vdc negative |
| 8 | + 24 | 24 Vdc positive |
| 9 | OUT (-) | 24 Vdc negative for safety TX photocell (monitored) |
| 10 | FCA 1 | Open limit switch Motor 1 |
| 11 | GND (-) | 24 Vdc negative |
| 12 | FCC 1 | Close limit switch Motor 1 |
| 13 | FCA 2 | Open limit switch Motor 2 |
| 14 | GND (-) | 24 Vdc negative |
| 15 | FCC2 | Close limit switch Motor 2 |
| LAMP | LAMP | Audio Alarm output |
| LOCK | LOCK | Output for electrical lock, max 5A pulse (DS2 - SW 4=OFF) $12 \mathrm{Vac} / 24 \mathrm{Vdc}$ Always ON (maglock): max 1 A (DS2 - SW 4=ON) 24 Vdc |
| MOT1 | MOT 1 | Motor 1 output ( first moving motor ) |
| MOT2 | MOT 2 | Motor 2 output ( second moving motor ) |
| USB A | USB | Firmware upgrade input |

## 3. SAFETY DEVICE CONNECTIONS

## Entrapment protection

To comply with the UL325 standard for gate operators every entrapment zone, as defined in ASTMF2200, must be protected by two independent entrapment protection devices. One of the devices is inherent in the EO24U control boards design, the other can be external, like a photocell or an edge sensor.

See this picture for the photocells positioning:


## Opening Safety Devices.

Are active only during the gate opening movement, and are suitable for protecting the area between the opening leaves and fixed obstacles (walls, etc) against the risk of entrapment

## Closing Safety Devices:

Are active only during the gate closing movement, and are suitable for protecting the closing area against the risk of entrapment.

## Monitored Devices:

Additionaly the UL325 standard requires that every external entrapment protection device must be monitored for presence and correct operation. To comply with this requirement the EO24U control board uses the FAILSAFE function. This function tests the photocells before each movement of the operator. In case the test fails the movement is inhibited. This function is enabled by default on the Closing Safety Input and can be enabled on the Opening Safety Input using dip-switch 12 of DSI ON. The power supply negative of the transmitter must be connected to the OUT pin (No.9).
See Fig. A6, A7, A8, A10 for wiring examples.

Connection of One Pair of Monitored Closing Photocells


FSW GND OUT
CL OP GND +24


RX= Receiver Photocell
TX = Transmitter Ptotocell
Fig. A6


Connection of One Pair of Monitored Opening
Photocells and One Pair of Monitored Closing Photocells


CL OP GND +24


CLOSE SAFETY


RX = Receiver Photocell TX= Transmilter Ptotocell

Only one monitored photocell can be connected to the Closing or Opening safety inputs. More than one photocell or other device can be connected to the safety inputs, but they will not be monitored.
Other devices connected to the safety inputs must have normally closed contacts and wired in series with the main monitored sensor.
See the following example of one closing safety monitored photocell and one non monitored one.

Connection of Two Pairs of Closing Photocells, One
Monitored and One non Monitored


RX= Receiver Photocell
Fig. A8

Connection of One Pair of Closing Photocells (monitored), One Pair of Opening Photocells (monitored) and One pair of Opening/Closing Photocells (non monitored)
$\underbrace{\text { GSW }}_{\text {CL OPGND }}{ }_{\text {+24 }}^{\text {OUT }}$

CL OP GND +24


RX= Receiver Photocell TX= Transmilter Ptotocell

## Opening/Closing Safety Devices:

They operate during the gate opening and closing movements and are suitable to protect the opening and closing areas against the risk of impact. Typically these photocells work in combination with other monitored photocell protecting closing or opening entrapment zones. In that case they can't be monitored so they can only protect against potential impact on vehicles.


## 4. PROGRAMMING

### 4.1 DIP SWITCH DS1 SETTINGS FOR OPERATING LOGIC

| OPERATING LOGIC <br> DS 1: SW 1-SW 2 - SW 3 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LOGIC | SW 1 | SW 2 | SW 3 | $\begin{aligned} & \hline \text { PAUSE } \\ & \text { TIME } \end{aligned}$ | DESCRIPTION |
| E (default) Semiautomatic | OFF | OFF | OFF | NO | One command opens, the next one closes. A command during opening stops the gate |
| A <br> Automatic | ON | ON | ON | $\begin{aligned} & \hline 0-4 \\ & \text { min } \end{aligned}$ | One command opens, waits for the pause time an then closes automatically |
| S Security | OFF | OFF | ON | $\begin{aligned} & 0-4 \\ & \text { min } \end{aligned}$ | One command opens, waits for the pause time and then closes automatically. If the closing safety is activated or another command is given during the pause time it closes. A maintained open command will not hold the gate open |
| EP Semiautomatic step by step | OFF | ON | OFF | NO | One command opens, the next one closes. During the movement a command stops the gate |
| AP <br> Automatic step by step | OFF | ON | ON | $\begin{aligned} & 0-4 \\ & \text { min } \end{aligned}$ | One command opens, waits for the pause time and then closes automatically. A command during the pause time holds the gate open |
| SP <br> Security step by step | ON | OFF | OFF | $\begin{aligned} & 0-4 \\ & \text { min } \end{aligned}$ | One command opens, waits for the pause time and then closes automatically. If the closing safety is activated during pause time the gate closes in 5 s . A command during pau- se time holds open the gate |
| $B$ <br> Manned Pulsed | ON | OFF | ON | NO | An open A command opens the gate, an open B command closes the gate |
| C <br> Manned Constant | ON | ON | OFF | NO | Holding open A active opens the gate, holding Open B active closes the gate |

For more details on the operating logics please refer to Chapter 11 - Function Logics

### 4.2 ADJUSTING TRIMMERS



TR 4 - SENSITIVITY ADJUSTEMENT FOR OBSTACLE DETECTION FOR MOTOR 1 AND MOTOR 2
Turn clockwise to increase the sensitivity for obstacle detection.
See Par. 6.3 for more details about the obstacle detection feature

TR 5 - PAUSE TIME ADJUSTMENT ( 0-4 min. )
Turn clockwise to increase the pause time.


Dip switches DS1: 1 to 3 need to be set for an operating mode with PAUSE time for this adjustment to have any effect

[^0]BOARD SETUP
DS 1: SW 4 to SW 12

| OPENING DELAY | SW 4 | The opening of leaf 2 is delayed after the opening of leaf 1 . This is to avoid the gate leafs interfering with each other during the initial part of the movement. In case there is only one leaf it has no effect. |
| :---: | :---: | :---: |
| 0 sec (default) | OFF |  |
| 2 sec | ON |  |
| REVERSE AND LAST STROKE | SW 5 | If active, before opening, while the gate is closed, the motors thrust to close for 2 s to facilitate the release of the electric lock. At closing the motors are activated for a final stroke after slowdown to facilitate locking of the electric lock. |
| inactive (default) | OFF |  |
| active | ON |  |
| MAX THRUST AT STARTUP | SW 6 | With this fuction active the motors work at maximum force at startup (regardless of the force setting) during the initial phase of the movement. Useful for heavy leaves |
| inactive (default) | OFF |  |
| active for 3 sec | ON |  |
| AUTOMATIC OPENING IN CASE OF POWER FAILURE | SW 7 | If active and with the optional backup battery installed, the board will open the gate after one minute from the power failure and keep it open. Within the minute wait it's always possible to open and close the gate with a command. If the logic used has a pause time the board will close the gate when the power comes back. |
| inactive (default) | OFF |  |
| active | ON |  |
| CLOSING SAFETY LOGIC | SW 8 | With this function you can choose the behavior of the closing safety. With SW8 OFF the gate movement will be reversed as soon as the safety is active, with SW8 ON the gate will stop when the safety is active and it will reverse only when the safety is deactivated. |
| immediate reverse (default) | OFF |  |
| reverse when cleared | ON |  |
| SHADOW LOOP CONFIGURATION | SW 9 | Selects the behavior of the shadow loop function of the XIB accessory OFF: The shadow loop input is active only before a closing command, ignored in any other conditions <br> ON: The shadow loop input is active before a closing and before an opening command. If an open command is given and the shadow loop input is engaged the open command will be ignored even after the shadow loop input goes inactive. <br> NOTE: On the first power up of the board an open command will be always executed (even if the shadow loop is engaged), but at reduced speed. |
| active only on closing (default) | OFF |  |
| active on closing and opening | ON |  |
| EXTRA SENSITIVITY TO OBSTACLE DETECTION | SW 10 | If active this function allows to have an immediate reverse in case the gate hits a rigid obstacle. This function increases the safety of the gate operator, however it can generate unwanted obstacle detections. |


| inactive (default) | OFF |
| :---: | :---: |
| active | ON |
| 24 V ACCESSORY VOLTAGE | SW 11 |
| 24 V OFF in Battery Mode | OFF |
| 24 V ON in Battery Mode | ON |
| FAIL SAFE MODE | SW 12 |
| Closing Safety | OFF |
| Closing and Opening Safety | ON |

Selects the behavior of the 24 V accessory voltage during battery mode: OFF: The accessory voltage and BUS input are turned off in battery backup mode
ON: The accessory voltage and BUS input are always active even in battery backup mode

Selects the behavior of the Fail Safe (monitoring) mode:
OFF: Fail Safe is active on the closing safety photocell input (FSW CL) only ON: Fail Safe is active on both closing safety photocell input (FSW CL) and opening safety photocell input (FSW OP)
NOTE: if using the XIB interface the opening safety on it is also monitored. Refers to the XIB manual for further details.
4.4 DIP SWITCH DS2 SETTINGS FOR OPERATOR TYPE AND LOCK MODE

5. LED DIAGNOSTICS


FAAC

| L | DESCRIPTION | LED STATUS <br> In BOLD the normal state with gate closed and working |  |  |
| :---: | :---: | :---: | :---: | :---: |
| D |  | ON STEADY | OFF | BLINKING |
| 1 | LED BATERY | Board working on AC power | Board working on battery power or ext supply | Battery charging |
| 2 | LED + 24 | Main power present | Main power OFF |  |
| 3 | LED SET-UP |  | Normal operation | SLOW BLINK (1 sec. ON - 1 sec . OFF) SETUP needed |
|  |  |  |  | FAST BLINK ( 0.5 sec. ON -0.5 sec OFF) SET UP in in progress |
| 4 | LED ERROR | Board malfunction. See possible causes below | No errors | Error conditions. <br> See LED ERROR DISPLAY table |
| 5 | LED BUS_MON | Communication on Bus "2easy" OK | Communication bus "2Easy" inactive. Verify encoders for shorts | "2Easy" bus devices with the Same address. Verify encoder LEDs |
| 6 | LED USB2 |  | Software update done or USB key not present | USB key inserted and software Update in progress (DON'T Remove the USB key) |
| 7 | LED USB 1 |  | Normal operation | Number of flashes show version at power up: <br> No Flashes=1C \| One flash = 1D |
| 8 | LED DL 14 OPEN A INPUT (N.O.) | OPEN A active | OPEN A not active |  |
|  | ED DL 15 OPEN B INPUT (N.O.) | OPEN B active | OPEN B not active |  |
|  | LED DL 16 STOP INPUT (N.C.) | STOP non active | STOP active or wiring error |  |
|  | LED DL 17 FSW CL INPUT (N.C.) | Closing safety devices clear | Closing safety devices triggered or wiring error |  |
|  | LED DL 18 FSW OP INPUT (N.C.) | Opening safety devices clear | Opening safety devices triggered or wiring error |  |
| 9 | LED DL 19 FCAI: OPEN LIMIT SWITCH MOTI (N.C.) | Limit switch OFF or not used | Limit Switch activated |  |
|  | LED DL 20 FCCI: CLOSE LIMIT SWITCH MOTI (N.C.) | Limit switch OFF or not used | Limit Switch activated |  |
| 10 | LED DL 21 FCA2: CLOSE LIMIT SWITCH MOT2 (N.C.) | Limit switch OFF or not used | Limit Switch activated |  |
|  | LED DL 22 FCC2: CLOSE LIMIT SWITCH MOT2 (N.C.) | Limit switch OFF or not used | Limit Switch activated |  |


| BOARD MALFUNCTION ERROR POSSIBLE CAUSES | SOLUTIONS |
| :---: | :---: |
| There were two consecutive obstacle detections (the audio alarm also should sound) | Remove obstructions |
| One of the motor driver components has failed | The board needs to be repaired |
| 24 V accessory power missing | The board needs to be repaired |
| The idle current in one of the motors is out of range | Check the motors |
| Both limit switches are active at the same time | Check the limit switches |
| Input voltage from the power supply is out of range | Check DC input voltage |

The diagnostic LED shows only one error condition at a time, with the priority of the below table. In case there is more than one error once one is eliminated the LED will show the next

| LED ERROR DISPLAY |  |  |
| :---: | :--- | :--- |
| NUMBER OF <br> FLASHES | ERROR CONDITION | SOLUTION |
| 1 | OBSTACLE DETECTION | Remove the obstacle, Check force and sensitivity settings |
| 2 | BOARD IN SLEEP MODE <br> (Slow blinking means that the automatic open <br> in case of power failure function is active) | Verify the presence of AC power |
| 3 | MOTOR 1 FAILURE | Inspect wiring to motor. If the wiring is good replace motor 1 |

## 6. TIME LEARNING (SET-UP)

After powering up the board for the first time or when the board will need it the setup LED will blink at a slow frequency to indicate that the setup procedure to learn the running times is needed.

The setup can be redone at any time by pressing and holding the setup button as indicated below. The setup cannot be done until the safeties and stop inputs are wired.

After the setup first movement, if the leafs are opening instead of closing you need to reverse the wires going to the motor that moves in the wrong direction

### 6.1 AUTOMATIC TIME LEARNING

WARNING: If the time learning setup is done automatically then the slow down points are set by the board on his own

## Move the leafs to the mid position Very important for a good result

1. Press and hold the SETUP button until the SETUP LED lights up, wait about 3 sec . until it turns off and then release it immediately. NOTE: If you wait too long to release it the manual set-up will start. The LED will blink during the setup procedure
2. Leaf 2 (if present) starts to move slowly in closing direction, stopping when it reaches the mechanical stop or FCC2.
3. Leaf 1 begins to move slowly in closing direction, stopping when it reaches the mechanical stop, or FCC1.
4. Leaf 1 starts to move slowly in opening direction, followed by leaf 2 (if present) still slowly.
5. When they both reach the open mechanical stop or FCA1 and FCA2 they stop and reverse, leaf 2 (if present) automatically starts closing at full speed followed by leaf 1 .
6. When they reach the close mechanical stop or FCCl and

FCC2 both leafs stop and leaf 1 restarts automatically opening at full speed followed by leaf 2 (if present).
7. If you selected an automatic logic the board will wait for the pause time and then closes the gate automatically. Otherwise you have to give an OPEN command to close the gate.

### 6.2 MANUAL TIME LEARNING

WARNING: If the manual time learning setup is done then the slow down points must be set by the installer during the procedure. Slow down is required for proper operation.

## Move the leafs to the mid position Very important for a good result

1. Press and hold the SETUP button until the SETUP LED lights up, keep it pressed for about 3 sec . until it turns off and keep it pressed more until the leaf 2 (if present) starts moving slowly. The LED will blink during the setup procedure
2. Leaf 2 will move in closing direction until it reaches the mechanical stop or FCC2
3. Leaf 1 starts moving slowly until it reaches the mechanical stop or FCCl
4. Leaf 1 starts moving in opening direction at the set speed (trimmer speed).
5. At the point where you want the slowdown to start give an OPEN A command with the push button or the remote that is already stored in memory. Leaf 1 starts to slow down and stops when it reaches the mechanical stop or FCA1.
6. Leaf 2 starts moving in opening direction at the set speed (trimmer speed)
7. At the point where you want the slowdown to start give an OPEN A command with the push button or the remote that is already stored in memory. Leaf 2 starts to slow down and stops when it reaches the mechanical stop or FCA2.
8. Leaf 2 starts to close at the set speed (trimmer speed).
9. At the point where you want the slowdown to start give an OPEN A command with the push button or the remote that is already stored in memory. The leaf 2 starts to slow down and stops when it reaches the mechanical stop or FCC2.
10. Leaf 1 starts to close at the set speed (trimmer speed).
11. At the point where you want the slowdown to start give an OPEN A command with the push button or the remote that is already stored in memory. Leaf 1 starts to slow down and stops when it reaches the mechanical stop or FCC 1.
12. The manual time learning procedure is complete.

After time learning test the gate to set the force, speed and sensitivity using the trimmers.


1. Apply resistance to the gate and adjust the Force to make sure that the operator creates enough thrust to reliably move the leaf.
2. Set the desired speed. Keep the speed relatively low on big and heavier gates.
3. After Force and Speed are set to the desired settings adjust the Sensitivity so the gate reverses promptly after hitting a rigid object.
4. After all the adjustments are done perform setup again.

### 6.3 OBSTACLE DETECTION FUNCTION

The obstacle detection function is achieved by controlling the current absorption and / or through the encoder connected to the motors.
If the gate encounters an obstacle during the movement of opening or closing, the obstacle detection function is activated and the operator reverses the direction of the gate.
In case of a second consecutive obstacle the operator stops the gate right away and any further command is inhibited. To re-enable the automation, you must remove power (and disconnect batteries if present) or open the STOP contact input. The Audio Alarm output will be active until this "reset".

This is a more detailed description of what happens after an obstacle detection:

## Gate opening, obstacle detected:

The gate reverses partially (for 3 sec .) and STOPS. After that the gate is in a halfway position or completely closed.

If an open_A command is received, the gate tries to open from the current position:

- If there is another obstacle detection: the gate stops completely, the alarm goes off
- If the gate reaches the open position: the obstructions count is reset, the gate returns to normal operations


## Gate closing, obstacle detected:

The gate reverses partially (for 3 sec .) and STOPS. After that the gate is in a halfway position or completely open.

If an open_A command is received in NON Automatic mode

- if the gate was not completely open: execute an open
- if the gate was completely open: execute a close

If an open_A command is received in Automatic mode:

- if the gate was not completely open: execute an open, wait for the pause time and then closes.
- if the gate was completely open: reload the pausetime, and then closes

If there is another obstacle detection: the gate stops completely, the alarm goes off.
If the gate reaches the close position: the obstructions count is reset, the gate returns to normal operations

## 7. ENCLOSURE

The EO24U board is supplied on a panel that fits in a $16 \times 14^{\prime \prime}$ enclosure.


On the back panel there are: the control board, the power supply and additional accessories.


## 8. POWER CONNECTION

## AC POWER GUIDELINES:

THE EO24U control board and power supply uses a single phase AC power line to operate, charge the batteries, and power gate accessories. Use the following guidelines when installing the AC power:

1. Check the local wiring codes in all cases and follow all local building codes. Wiring and hookup should be performed by a qualified electrician/installer only.
2. AC power should be supplied from a circuit breaker panel and must have its own dedicated circuit breaker. This supply must include a green ground conductor.
3. Use copper conductor wires with liquid tight flexible conduit UL listed for electric cable protection

## 14 AWG, 600V, $80^{\circ} \mathrm{C}$ Terminal Block max Torque 2.1 Nm

4. Properly ground the gate operator to minimize or prevent damage from power surges and/or lightning. Use a grounding rod if necessary. A surge suppressor is recommended for additional protection.

## AC POWER CONNECTION

To connect AC power to the controller:

1. Turn the circuit breaker for the AC gate operator power OFF before connecting the AC input wires.
2. Turn OFF the Power Switch located on the left side of enclosure before connecting the AC input wires.
3. Connect the $A C$ input wires to the $A C$ terminal located on the top left of the control box. See diagram below.
4. Batteries must be installed after the AC power is on. See Battery Power Connection.


### 8.1 POWER SUPPLY

The E024U board is powered by a high efficiency switching power supply that takes 115 VAC input and provides 36 VDC to power the board. On the power supply board there is only one repleaceble fuse: 6.3A timed


## 9. BACKUP BATTERY

The EO24U board allows the connection of a 24 V backup battery to provide power to operate the gate during blackouts. For more details about how the boards handles the loss of main power and how to configure its behaviour please see par 4.3 and DS1 switch 7.

To connect the battery use the provided cable and jumper. Plug the jumper from the red (+) terminal of first battery to the black (-) terminal on the second battery and then connect the battery cable red wire to the red ( + ) terminal on the second battery and the black wire to the black (-) terminal on the first battery. Finally plug the cable on the BATTERY connector on the board.


### 9.1 DISABLE THE BATTERY CHARGER

The internal battery charger must be disabled to use an external charger. To disable the battery charger unplug jumper J24

J24 PRESENT = BATTERY CHARGING ACTIVE J24 NOT PRESENT = BATTERY CHARGING NOT ACTIVE


## 10. FIRMWARE UPGRADE

The E024U board keeps the operating firmware in a field programmable memory, it can be easily upgraded through the on board USB port


For the upgrade you need a USB Flash Drive, where you have to copy the file supplied by FAAC. Then follow these steps:

1. Disconnect the batteries if they are present.
2. Turn the AC power off and insert the Flash Drive into the USB A input on the board
3. Turn the AC power back on. The USB2 LED will start to flash to confirm the beginning of the software update. (WARNING: DON'T TURN THE POWER OFF OR REMOVE THE FLASH DRIVE UNTIL THE USB2 LED TURNS OFF.
4. Wait until the USB 2 LED turns off
5. Remove the USB Flash drive.
6. Cycle power, reconnect the batteries if needed and execute a new SETUP procedure (See chapter 6)

## $\triangle$

WARNING: Only upgrade the firmware with the proper file supplied by FAAC, otherwise the board could be damaged

### 10.1 VERIFY THE FIRMWARE VERSION

On initial power up watch the LED USB 1 on the bottom left of the board. The number of flashes indicate the version:
No Flashes = Version 1C, refer to manuals dated Jan. 2016 and before.
1 FLash = Version 1D refer to manuals dated after Jan. 2016


FAAC
11. FUNCTION LOGICS

| LOGIC "E" | PULSES |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SYSTEM STATUS | OPEN A | OPEN B | STOP | FSW OP | FSW CL | FSW CL/OP |
| CLOSED | opens the leaves | opens leaf 1 | no effect (OPEN disabled) | no effect (OPEN disabled) | no effect | no effect (OPEN disabled) |
| OPENING | stops operation <br> (1) | stops operation | stops operation | immediately reverses at closing | no effect | stops and opens at release (OPEN stops - saves CLOSE) |
| OPEN | recloses leaves immediately (1) | recloses leaves immediately | no effect (OPEN/CLOSE disabled) | no effect | no effect (CLOSE disabled) | no effect (OPEN/CLOSE disabled) |
| CLOSING | reopens leaves immediately | reopens leaves immediately | stops operation | no effect | reverses at opening | stops and opens at release (OPEN stops - saves CLOSE) |
| BLOCKED | closes leaves | closes leaves | no effect (OPEN/CLOSE disabled) | no effect (OPEN disabled) | no effect (CLOSE disabled) | no effect (OPEN stops saves CLOSE) |

(1) if the cycle began with OPEN-B (leaf 1), both leaves are activated at opening

| LOGIC "A" | PULSES |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SYSTEM STATUS | OPEN A | OPEN B | STOP | FSW OP | FSW CL | FSW CL/OP |
| CLOSED | opens and closes after pause time | opens leaf 1 and closes after pause time | no effect (OPEN disabled) | no effect (OPEN disabled) | no effect | no effect (OPEN disabled) |
| OPENING | no effect (1) | no effect | stops operation | reverses at closing | no effect | stops and opens at release (saves CLOSE) |
| OPEN IN PAUSE | reloads pause time (1) | reloads pause time of released leaf | stops operation | no effect | recharges pause time (CLOSE disabled) | recharges pause time (CLOSE disabled) |
| CLOSING | reopens leaves immediately | reopens leaves immediately | stops operation | no effect | reverses at opening | stops and opens at release (saves CLOSE) |
| BLOCKED | closes leaves | closes leaves | no effect (OPEN/CLOSE disabled) | no effect (OPEN disabled) | no effect (CLOSE disabled) | no effect (OPEN/CLOSE disabled) |

(1) if the cycle began with OPEN-B (leaf 1), both leaves are activated at opening

| LOGIC "S" | PULSES |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SYSTEM STATUS | OPEN A | OPEN B | STOP | FSW OP | FSW CL | FSW CL/OP |
| CLOSED | opens and closes after pause time | opens released leaf and closes after pause time | no effect (OPEN disabled) | no effect (OPEN disabled) | no effect | no effect (OPEN disabled) |
| OPENING | no effect (1) | no effect | stops operation | reverses at closure | continues to open and recloses immediately | stops and opens at release (saves CLOSE) |
| OPEN IN PAUSE | recloses leaves immediately (1) | recloses leaves immediately | stops operation | no effect | stops and, at release, closes | stops and, at release, closes |
| CLOSING | reopens leaves immediately | reopens leaves immediately | stops operation | no effect | reverses at opening (see DS1-SW8) and closes immediately at end | stops and opens after release and closes immediately at end |
| BLOCKED | closes leaves | closes leaves | no effect (OPEN/CLOSE disabled) | no effect (OPEN disabled) | no effect (CLOSE disabled) | no effect (OPEN/CLOSE disabled) |

(1) if the cycle began with OPEN-B (leaf 1), both leaves are activated at opening

| LOGIC "EP" | PULSES |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SYSTEM STATUS | OPEN A | OPEN B | STOP | FSW OP | FSW CL | FSW CL/OP |
| CLOSED | opens the leaves | opens leaf 1 | no effect (OPEN disabled) | no effect (OPEN disabled) | no effect | no effect (OPEN disabled) |
| OPENING | stops operation (1) | stops operation | stops operation | immediately reverses at closure | no effect | stops and opens at release (OPEN stops saves CLOSE) |
| OPEN | recloses leaves immediately (1) | recloses leaves immediately | no effect (OPEN/CLOSE disabled) | no effect | no effect (CLOSE disabled) | no effect (OPEN/CLOSE disabled) |
| CLOSING | stops operation | stops operation | stops operation | no effect | reverses at opening | stops and opens at release (OPEN stops saves CLOSE) |
| BLOCKED | restarts moving in opposite direction. Always closes after STOP | restarts moving in opposite direction. Always closes after STOP | no effect (OPEN/CLOSE disabled) | no effect (OPEN disabled) | no effect (CLOSE disabled) | no effect (OPEN stops saves CLOSE) |

(1) if the cycle began with OPEN-B (leaf 1), both leaves are activated at opening

| LOGIC "AP" | PULSES |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SYSTEM STATUS | OPEN A | OPEN B | STOP | FSW OP | FSW CL | FSW CL/OP |
| CLOSED | opens and closes after pause time | opens leaf 1 and closes after pause time | no effect (OPEN disabled) | no effect (OPEN disabled) | no effect | no effect (OPEN disabled) |
| OPENING | stops operation <br> (1) | stops operation | stops operation | reverses at closing (saves OPEN) | no effect | stops and opens at release (OPEN stops saves CLOSE) |
| OPEN IN PAUSE | stops operation <br> (1) | stops operation | stops operation | no effect | recharges pause time (CLOSE disabled) | recharges pause time (CLOSE disabled) |
| CLOSING | reopens leaves immediately | reopens leaves immediately | stops operation | no effect | reverses at opening (see DS1-SW8) | stops and opens at release (OPEN stops saves CLOSE) |
| BLOCKED | closes leaves | closes leaves | no effect (OPEN/CLOSE disabled) | no effect (OPEN disabled) | no effect (CLOSE disabled) | no effect (OPEN/CLOSE disabled) |

(1) if the cycle began with OPEN-B (leaf 1), both leaves are activated at opening

| LOGIC "SP" | PULSES |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SYSTEM STATUS | OPEN A | OPEN B | STOP | FSW OP | FSW CL | FSW CL/OP |
| CLOSED | opens and closes after pause time | opens leaf 1 and closes after pause time | no effect (OPEN disabled) | no effect (OPEN disabled) | no effect | no effect (OPEN disabled) |
| OPENING | stops operation <br> (1) | stops operation | stops operation | reverses at closure | continues to open and recloses immediately | stops and opens after release and closes immediately at end (OPEN stops - saves CLOSE) |
| OPEN IN PAUSE | recloses leaves immediately (1) | recloses leaves immediately | stops operation | no effect | stops and, at release, closes | stops and, at release, closes |
| CLOSING | stops operation | stops operation | stops operation | no effect | reverses at opening | stops and opens at release (saves CLOSE) |
| BLOCKED | restarts moving in opposite direction. Always closes after STOP | restarts moving in opposite direction. Always closes after STOP | no effect (OPEN/CLOSE disabled) | no effect (OPEN disabled) | no effect (CLOSE disabled) | no effect (OPEN/CLOSE disabled) |

(1) if the cycle began with OPEN-B (leaf 1), both leaves are activated at opening

| LOGIC "B" | PULSES |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SYSTEM STATUS | OPEN A | OPEN B | STOP | FSW OP | FSW CL | FSW CL/OP |
| CLOSED | opens the leaves | no effect | no effect (OPEN disabled) | no effect (OPEN disabled) | no effect | no effect (OPEN disabled) |
| OPENING | no effect | closes leaves | stops operation | reverses at closure | no effect | stops and, at release, closes (saves OPEN/CLOSE) |
| OPEN | no effect | closes leaves | no effect (OPEN/CLOSE disabled) | no effect | no effect (CLOSE disabled) | no effect (OPEN/CLOSE disabled) |
| CLOSING | opens the leaves | no effect | stops operation | no effect | reverses at opening | stops and opens at release (saves OPEN/CLOSE) |
| BLOCKED | opens the leaves | closes leaves | no effect (OPEN/CLOSE disabled) | no effect (OPEN disabled) | no effect (CLOSE disabled) | no effect <br> (OPEN/CLOSE disabled) |


| LOGIC "C" | CONTINUOS COMMANDS |  | PULSES |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SYSTEM STATUS | OPEN A | OPEN B | STOP | FSW OP | FSW CL | FSW CL/OP |
| CLOSED | opens the leaves | no effect | no effect <br> (OPEN disabled) | no effect <br> (OPEN disabled) | no effect | no effect <br> (OPEN disabled) |
| OPENING | no effect | closes leaves | stops operation | reverses at closure | no effect | stops and, at release, closes <br> (saves <br> OPEN/CLOSE) |
| OPEN | no effect | closes leaves | no effect <br> (OPPN/CLOSE <br> disabled) | no effect | no effect <br> (CLOSE disabled) | no effect <br> (OPEN/CLOSE disabled) |
| CLOSING | opens the leaves | no effect | stops operation | no effect | reverses at opening | stops and opens at release <br> (saves <br> OPEN/CLOSE) |
| BLOCKED | opens the leaves | closes leaves | no effect <br> (OPEN/CLOSE <br> disabled) | no effect <br> (OPEN disabled) | (CLOSE disabled) <br> no efect | no effect <br> (OPEN/CLOSE disabled) |

## 12. ACCESSORIES

### 12.1 SHADOW LOOP INTERFACE (p/n 790062)

Through the use of the XIB interface board you can connect an additional loop detector (center or shadow) to the EO24U board to keep the gate open if vehicles are obstructing the closing path. With a dip switch setting the shadow loop can function on both opening and closing (see section 4.3)


XIB board description

| J1 ( RED ) | Connects to "2easy" BUS input on the E024U |
| :--- | :--- |
| J2 ( RED ) | Terminal for the connection of the encoder |
| J3 CL (GREEN) | Terminal for the NC connection of the shadow loop <br> detector |
| J3 OP (GREEN ) | Terminal for the NC connection of second open <br> safety |
| DL1 | LED for diagnostics of devices connected to the J3 <br> OP |
| DL2 | LED for diagnostics of devices connected to the J3 <br> CL |

INSTALLING THE INTERFACE

1. Turn power OFF
2. Plug in the XIB interface to the 2EASY connector on the EO24U board
3. Wire the shadow loop detector NC output to the CL input on the XIB board as in figure below
4. Connect Common from loop detector to GND (terminal 6) on E024U
5. If no second open safety device is present jump out the OP input on XIB board to GND (terminal 6) on the EO24U
6. Wire the encoder (if needed) to J2
7. Refer to Fig. All for the wiring schematic
8. Turn power back ON
9. Press and release the SW1 button quickly. The board will recognize that the XIB board has been removed
10. Re-program run time if needed.


## REMOVING THE INTERFACE

1. Turn power OFF
2. Unplug the board and remove the wiring
3. Move the encoder wires (if present) to the 2EASY connector on the board
4. Turn power back ON
5. Verify that leaf $1 \& 2$ lights on the encoder are correct
6. Press and release the SW1 button quickly. The board will recognize that the XIB board has been removed
7. Re-program run time if needed.

NOTE:

- Do not connect the shadow loop detector in series with regular closing safety devices.
- If the EO24U board doesn't have the correct software installed the shadow loop will act as a normal closing safety, detecting also the gate itself and not allowing the closing movement to complete. Please contact technical support for assistance in that case.


## SECOND OPEN SAFETY INPUT

The OP input on the XIB board can be used as a second monitored open safety input.
When open safety monitoring is turned ON on the EO24U board (Dip SW 12 ON) the OP input on the XIB (J3 OP) is monitored and can be used to protect an entrapment zone. See Fig. A12a/b for the connections.
In case only one opening safey input is needed and the XIB board is present connect the opening safey photocell to FSW OP on the EO24U and J3 OP on the XIB in parallel. See Fig. Al3a/b for the connections.


+24 OUT


TRANSMITTER PHOTOCELL

Fig. A13b

|  |  |  |  |  |  | OFF | SLOW FLASHING <br> (FLASH EVERY 5 secs.) | ON STEADY | FAST FLASHING (FLASH EVERY 0.5 sec) |
| :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| DL1 | "XIB" board <br> malfunction <br> or no power | J3 OP terminal open <br> (missing jumper on the OP <br> input) | J3 OP terminal closed <br> (normal condition) | Error condition on the BUS |  |  |  |  |  |
| DL2 | "XIB" board <br> malfunction <br> or no power | J3 CL terminal open <br> (loop detector active or not <br> connected) | J3 CL terminal closed <br> (loop detector in idle <br> condition) |  |  |  |  |  |  |

### 12.2 LOOP DETECTORS INTERFACE (p/n 2670)

The Loop Detector Interface allows connection of up to three plug-in detectors associated with standard functions. The board is designed to fit in the FAAC standard $16^{\prime \prime} \times 14^{\prime \prime}$ enclosure on the existing DIN rail. To connect the interface board:

1) Connect the 2EASY BUS from the EO24U to the interface board (no polarity) - Green Wires
2) Connect pin 8 on the EO24U board ( +24 V ) to the +24 input on the interface board - Red Wire
3) Connect pin 7 on the EO24U board (GND) to the GND input on the interface board - Black Wire
4) Connect the loops to the interface board as in the figure below

Turn the power on on the E024U board. The LED on the interface board will blink briefly and then will stay ON solid if the BUS connection is working correctly.
IMPORTANT: Briefly press the SW1 button on the EO24U board to make it aware of the presence of the additional interface board.
To make sure the board is working properly you can check the behaviour of BUS LED on the EO24U board. It will be normally on when none of the loop detectors is active. If any of the detectors is activated the LED will turn off.


NOTE: You can use the shadow loop interface OR the loop detectors interface but not both at the same time. If two monitored open safeties are required the additional loop detectors (other than the shadow) must be wired directly to the E024U board.

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NOTES:

NOTES:


[^0]:    TR6 - CLOSING DELAY OF LEAF 1 OVER LEAF 2 ADJUSTMENT ( 0-15 sec )
    Turn clockwise to increase the delay

